

One Approach for Identification of Brain Signals for Smart Devices Control

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Abstract: Nowadays the UX design become on a next level. Together with new way of interaction are introduced as finger and hand movement. The technology offer and thought-driven approach with so called brain-computer interface (BCI). This possibility opens new challenges for uses as well as for designers and researchers.

More than 15 years there are devices for brain signal interception, such as EMotiv Epoc, Neurosky headset and others. The reliable translation of user commands to the app on a global scale, with no leaps in advancement for its lifetime, is a challenge. It is still un-solve for modern scientists and software developers. Success requires the effective interaction of many adaptive controllers: the user's brain, which produces brain activity that encodes intent; the BCI system, which translates that activity into the digital signals; the accuracy of aforementioned system, computer algorithms to translate the brain signals to commands. In order to find out this complex and monumental task, many teams are exploring a variety of signal analysis techniques to improve the adaptation of the BCI system to the user. Rarely there are publications, in which are described the used methods, steps and algorithms for discerning varying commands, words, signals and etc.

This article describes one approach to the retrieval, analysis and processing of the received signals. These data are the result of researching the capabilities of Arduino robot management through the brain signals received by BCI.

Key words: Integrated information systems, Brain Computer Interface, BCI, BIG Data, data processing, sensors, EMotiv

1. Introduction

The main goal of this article is to highlight the ability to reliably discern the varying brain signals. In a perspective, the clear signal identification will ensure development mathematical tools and algorithms for electrical devices, such as wheelchairs and other similar devices needed by people with reduced communication and motor abilities[1,2]. Also, research will enhance the utilization of the Internet of Things (IoT). Unfortunately, the standard distributed with widespread BCI devices' interface has a very limited command dictionary[3,4]. Our team analyses the necessary BCI signals for driving a remote control car. For the needs of our research, we have determined eight simplified base commands - START, STOP, LEFT, RIGHT, FORWARD, BACKWARD, FASTER and SLOWER. In this article the analyses of only two commands - START and STOP is described as well as the differences between these two commands.

The brain emits ElectroEncephaloGraphic(EEG) signals, which are caught by the 5 electrodes of EMOTIV Insight 5+ device. The raw EEG data is picked up by the electrode and are sent via the Bluetooth into the

computer. This device can discern 5 signals(Fig. 1):

- AF3 – Attention
- T7 – Verbal memory
- Q1 – Visual Processing
- T8 – Emotional memory
- AF4 – Judgment

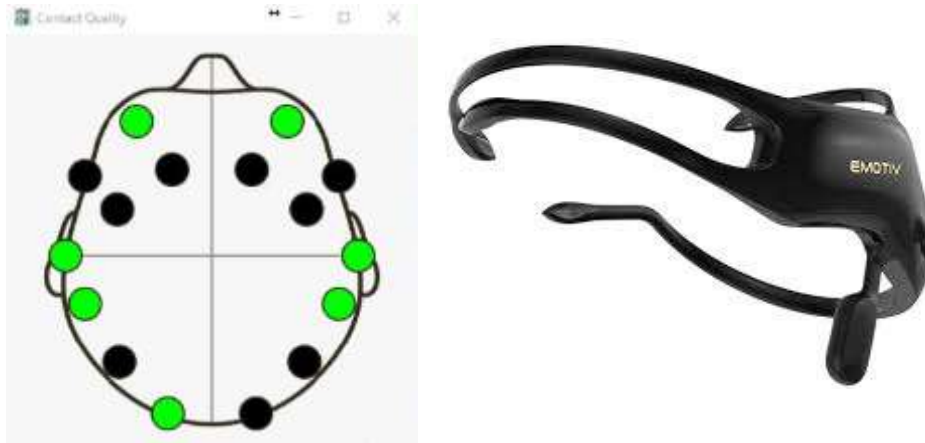


Fig. 1. Map of the electrodes in Epoc Insight 5 channels.

The received signals are store into database The application BrainData (Fig. 2) developed in university laboratory maintain this process. The application features includes the possibilities for the simultaneous recording and processing of BIG DATA[3]. This means different types of data are recorded at the same time, such as: raw data from BCI, the subject shown at that moment, the video recording of the experiment and other. The system allows interoperability - receiving the data from the BCI system, processing, exporting of the data to other systems and communication with other apps, which can use these data.

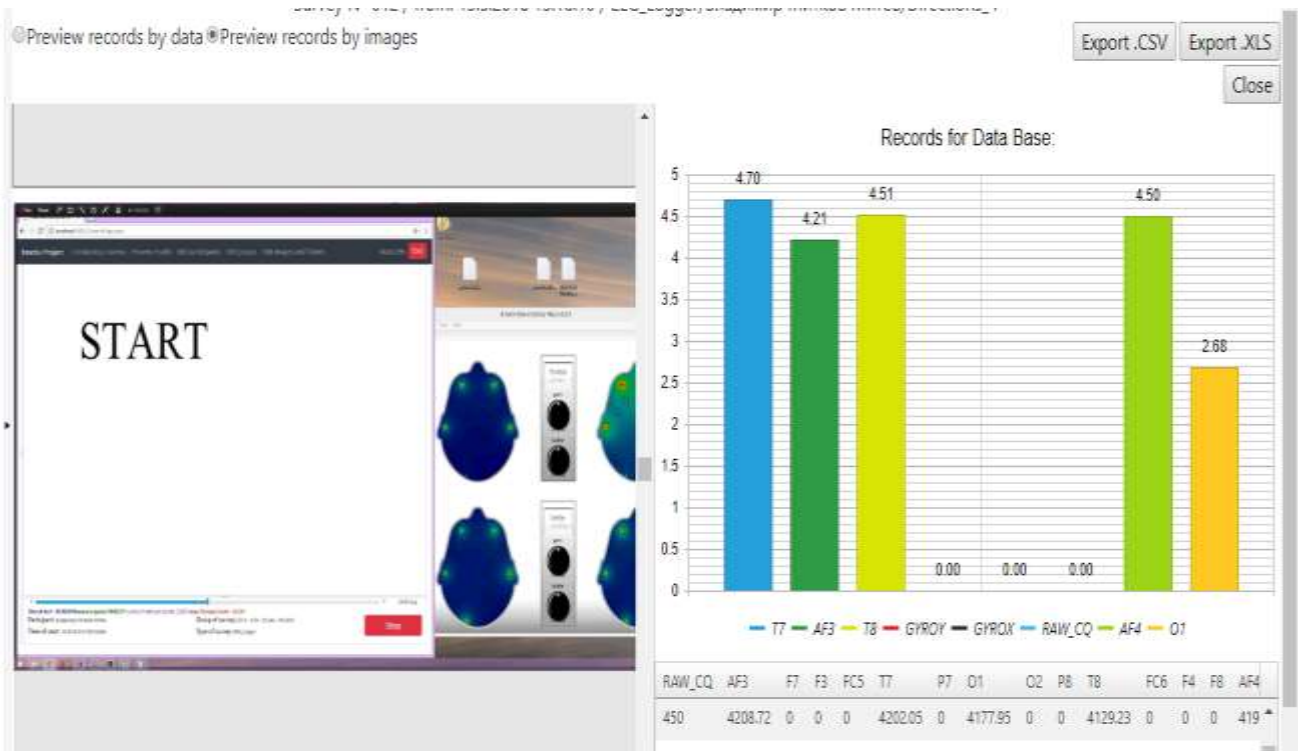


Fig. 2. Brain data.

The steps of creation process are: 1) Obtaining an EEG signal; 2) Inserting data into a database; 3) Filtering

and classification of EEG signals; 4) Processing of the data array; 5) Utilization of the already processed Smart Device Management data. The focus here is on the step 3 only.

2. Methods

2.1. Data Collection

The used data are collected during BCI experiments and analyzed offline. It will be described later.

There are 3 examinees. During the experiment, each participant see 8 different pictures (commands). Pictures are changed at different time intervals – 0.25, 0.5, 1 and 1.25 seconds in a random principle. Each participant, after seeing the picture, mentally commands and executes it. As was mention above the two opposit commands – START and STOP are observed. Each examinee made 7 attempts. Each command is shown more than 360 times in total, or 120 times for each participant.

In real time the signals received from the Epc are transferred via Bluetooth into the computer. Each trial are recorded 129 rows of data into the database. The count of the records is shown on Table 1. The data are obtained with SDK tool, provided by Emotiv ([github.com/Emotiv/ community-sdk](https://github.com/Emotiv/community-sdk)). The collecting information for the experiment, the commands, raw data and screen capture are recorded at the same time into the database, then data are exported and processed using MathLab environment.

Table 1. Count of the Experiments

	COMMAND	
	START	STOP
Count of the change pictures	369	367
Count of the rows whit signal data in one experiment	129	
All count of records	100396	99674

2.2. Data Processing

This research gives a useful insight understanding of the meaning for each Emotiv EEG Sensor.

The raw data, received during the display of the “Stop” command are shown on Table 2.

Table 2 Raw data – “START”

AF3	T7	O1	T8	AF4
4233.07	4572.24	4195.39	4188.37	4172.35
4233.52	4570.72	4225.62	4216.47	4179.49
.....
4229.48	4494.43	4231.28	4165.12	4176.22

The raw data, received during the display of the “Stop” command are shown on Table 3.

Table 3 Raw data – “STOP”

AF3	T7	O1	T8	AF4
4222.33	4555.69	4158.56	4197.81	4153.63
4253.96	4683.83	4149.65	4255.87	4136.59
.....
4209.40	4500.95	4244.27	4167.63	4147.19

2.3. Filtering the Signal

A main characteristics of the data, which are used for research and analysis, are to be accurate and valid. It is rarely possible because when data are copied from reality via a sensor/observer, through transmission and finally stored, it is susceptible to corruption for many reasons[6,7]. During the experiments it is impossible for the test subject to be permanently concentrated upon the given command. This leads to receiving unnecessary or false data in the stream. The original raw data is showing on Figure 3. At first glance the signals have big amplitudes. This data must be filtered.

The filtered stream of data are with exclusion of those which values differ by 50% from the average (Figure 4).

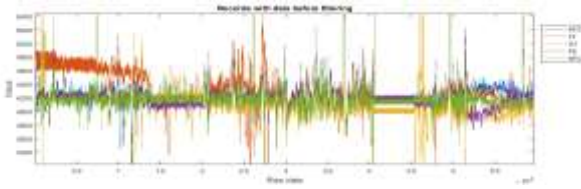


Figure 3 Raw data before filtering

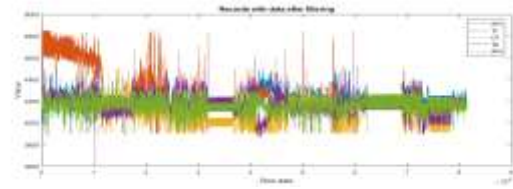


Figure 4 Raw data after filtering

On the Table 4 is shown the count of the records before and after filtering and percent of the excluded rows.

Table 4 rows and filtered rows

	START	STOP
All rows with data	100396	96794
Filtered rows	81432	81395
% excluded records	19%	16%

2.4. Processing Data

To distinguish data for different command is a crucial for this research, i.e. the identification of the data[8]. This is arrange by extracting the mean values, standard deviation and differentiate the meaning of the signal values on the each channel. The availability of distinct differences would indicate the possibility of distinguishing the incoming signals.

Mean value of the signal

The avg. values of each channel is calculated in a Matlab environment:

The resulting avg. values are shown on Table 5.

Table 5. AVG Values for Each Command and Each of the Channels

	AVA. values	
	START	STOP
AF3	4200,83764287520	4206,90253712517
T7	4261,67373675012	4259,72984825013
O1	4103,32124187518	4104,19762087510
T8	4166,84227274986	4165,75719124990
AF4	4156,81051724984	4159,94656387485

The graph for the resulting values is shown in the Fig. 5.

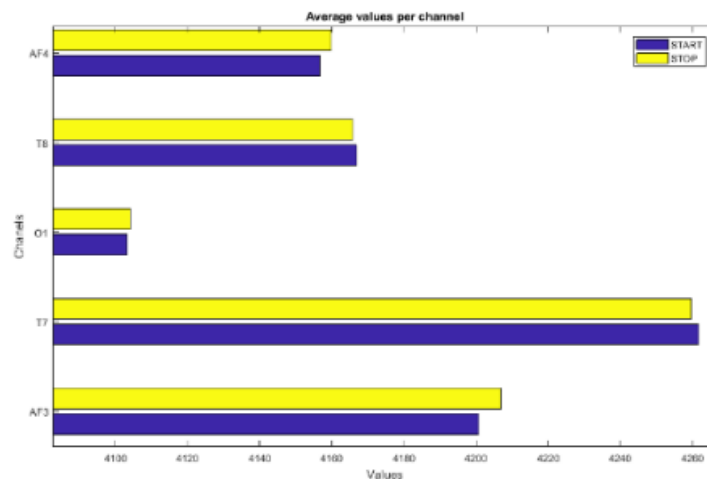


Fig. 5. AVG values for each command and each of the channels.

Standard deviation

The next step is calculating the standard deviation for each command and each of the channels.

The results show the following: The deviation is biggest at channel T7 and lowest at channels AF3 and AF4. In other words, AF3 and AF4 have the most durable signals, as shown in Table 6 and Fig. 6.

Table 6. STD Values for each Command and Each of the Channels

Chanel	STDEV(„START“)	STDEV(„STOP“)
AF3	79.4551	78.2322
T7	187.8361	184.6027
O1	100.1024	98.2479
T8	85.1357	86.1827
AF4	63.4918	62.3431

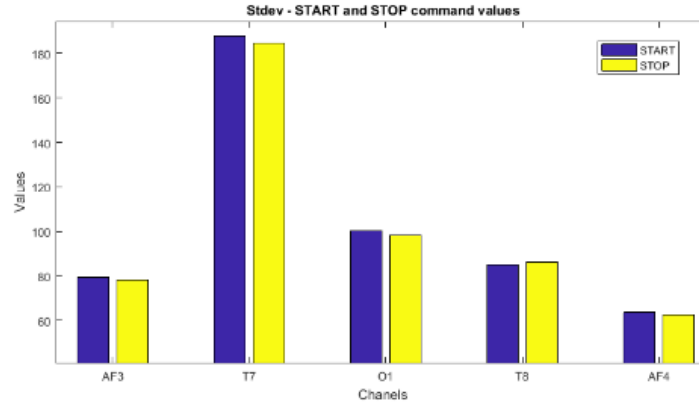


Fig. 6. Graph with STD values for each command and each of the channels.

The differences between the mean values in every channel

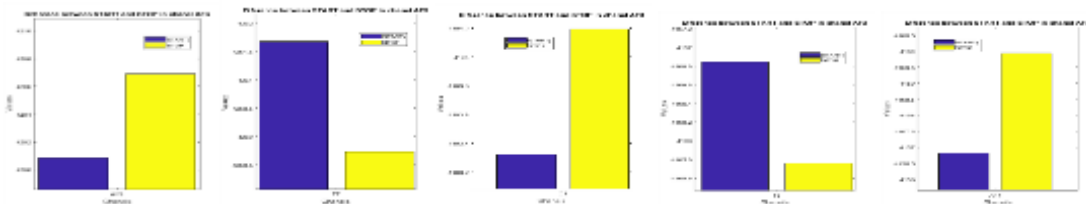
In a Matlab environment we calculated the differences between the mean values of the signals for each channel separately.

The resulting differences are shown in Table 7.

Table 7. Differences between the Values for Each Channel

	START - STOP
AF3	-6.0649
T7	1.9439
O1	-0.8764
T8	1.0851
AF4	-3.1360

Down are shown the differences between the values of every command in each individual channel.



3. Conclusions

Identification of the separate brain signals and using this for interaction driven devices will increase in the next years but first steps are done.

In this research application of several data processing as filtering, calculation of average values, average deviation shows clear difference between channels of the signals for each command. This can be used for the creation of suitable algorithms for the processing in real time. Using similar methods and approaches this will give the opportunity, with the acquisition of an expansive database with suitable commands and their base characteristics for the commanding of remote controlled devices.

Our team hopes in the future to build the necessary knowledge base for the various commands required for

direct device management using brain signals

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